

Basic linear algebra background

Vectors and matrices

Формальности
Група
mip23, fmin.xyz

We will treat all vectors as column vectors by default. The space of real vectors of length n is denoted by \mathbb{R}^n , while the space of real-valued $m \times n$ matrices is denoted by $\mathbb{R}^{m \times n}$. That's it: ¹

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

$$x^T = [x_1 \quad x_2 \quad \dots \quad x_n]$$

курс поговори

- ТЕСТЫ
- домашки после каждой темы
- проекты
- экзамен

$x \in \mathbb{R}^n, x_i \in \mathbb{R}$

Теоретический минимум

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Similarly, if $A \in \mathbb{R}^{m \times n}$ we denote transposition as $A^T \in \mathbb{R}^{n \times m}$:

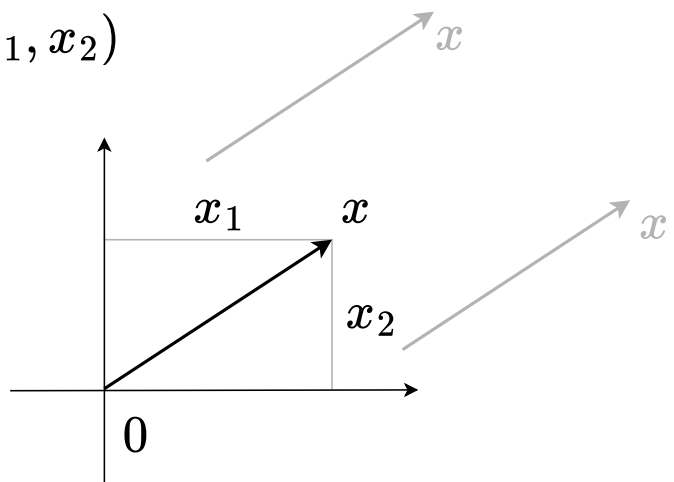
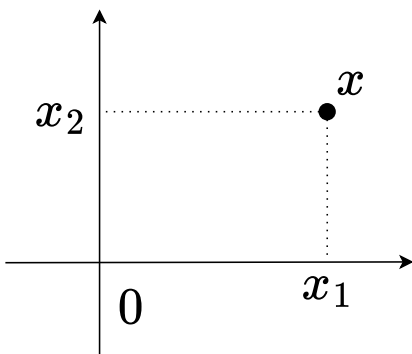
$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

$$A^T = \begin{bmatrix} a_{11} & a_{21} & \dots & a_{m1} \\ a_{12} & a_{22} & \dots & a_{m2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1n} & a_{2n} & \dots & a_{mn} \end{bmatrix}$$

Таблицы и сетки:
markdown + latex
LNU
latex
PDF
 $A \in \mathbb{R}^{m \times n}, a_i$

We will write $x \geq 0$ and $x \neq 0$ to indicate componentwise relationships

$$x^T = (x_1, x_2)$$



A matrix is symmetric if $A = A^T$. It is denoted as $A \in \mathbb{S}^n$ (set of square symmetric matrices of dimension n). Note, that only square matrix could be symmetric by definition.

A matrix $A \in \mathbb{S}^n$ is called **positive (negative) definite** if for all $x \neq 0 : x^T A x > (<) 0$

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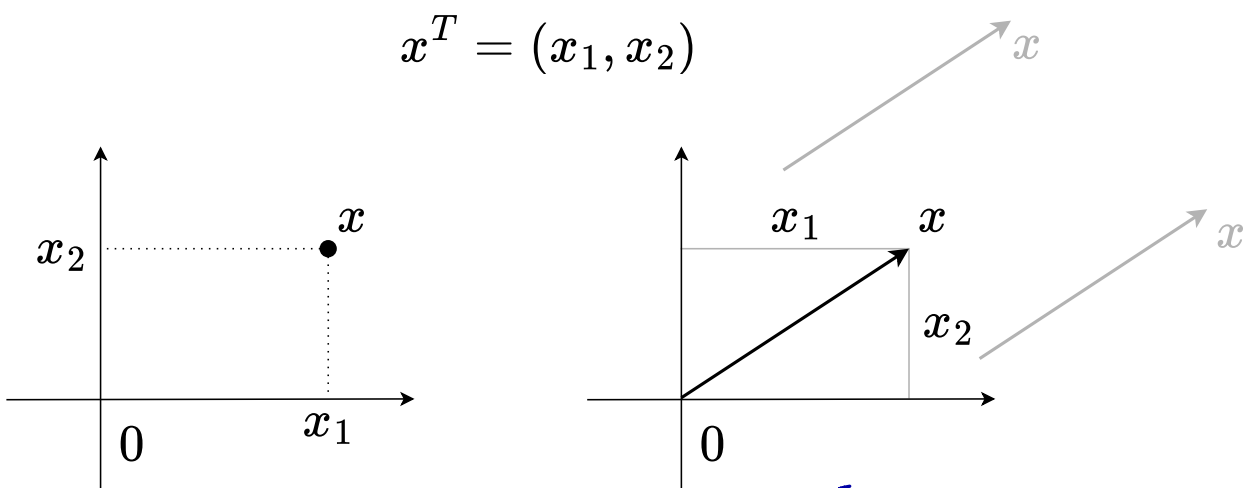
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$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad x^T = [x_1 \quad x_2 \quad \dots \quad x_n] \quad x \in \mathbb{R}^n, x_i \in \mathbb{R}$$

Similarly, if $A \in \mathbb{R}^{m \times n}$ we denote transposition as $A^T \in \mathbb{R}^{n \times m}$:

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \quad A^T = \begin{bmatrix} a_{11} & a_{21} & \dots & a_{m1} \\ a_{12} & a_{22} & \dots & a_{m2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1n} & a_{2n} & \dots & a_{mn} \end{bmatrix} \quad A \in \mathbb{R}^{m \times n}, a_i$$

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A matrix $A \in \mathbb{S}^n$ is called positive (negative) definite if for all $x \neq 0$: $x^T A x > (<) 0$

$$\begin{matrix} \{n \times n\} & \{n \times n\} & \{n \times 1\} \\ \{1 \times 1\} & & \end{matrix}$$

. We denote this as $A \succ (\prec) 0$. The set of such matrices is denoted as $\mathbb{S}_{++}^n (\mathbb{S}_{--}^n)$

A matrix $A \in \mathbb{S}^n$ is called **positive (negative) semidefinite** if for all $x : x^T A x \geq (\leq) 0$. We denote this as $A \succeq (\preceq) 0$. The set of such matrices is denoted as $\mathbb{S}_+^n (\mathbb{S}_-^n)$

QUESTION

Is it correct, that positive definite matrix has all positive entries?

Matrix and vector product

Let A be a matrix of size $m \times n$, and B be a matrix of size $n \times p$, and let the product AB be:

$$C = AB$$

$m \times p$ $m \times n$ $n \times p$

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then C is a $m \times p$ matrix, with element (i, j) given by:

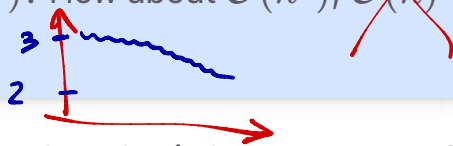
$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

This operation in a naive form requires $\mathcal{O}(n^3)$ arithmetical operations, where n is usually assumed as the largest dimension of matrices.

$\mathcal{O}(n^{\log_2 7})$

QUESTION

Is it possible to multiply two matrices faster, then $\mathcal{O}(n^3)$? How about $\mathcal{O}(n^2)$, $\mathcal{O}(n)$?



Let A be a matrix of shape $m \times n$, and x be $n \times 1$ vector, then the i -th component of the product:

$$z = Ax$$

$m \times 1$ $m \times n$ $n \times 1$

$\mathcal{O}(n^2)$

is given by:

$$z_i = \sum_{k=1}^n a_{ik} x_k$$

Remember, that:

- $C = AB \quad C^T = B^T A^T$
- $AB \neq BA$

- $e^A = \sum_{k=0}^{\infty} \frac{1}{k!} A^k$ - *матрица экспонента*
- $e^{A+B} \neq e^A e^B$ (but if A and B are commuting matrices, which means that $AB = BA$, $e^{A+B} = e^A e^B$)
- $\langle x, Ay \rangle = \langle A^T x, y \rangle$

Norms and scalar products

Norm is a **qualitative measure of smallness of a vector** and is typically denoted as $\|x\|$.

The norm should satisfy certain properties:

- 1 $\|\alpha x\| = |\alpha| \|x\|, \alpha \in \mathbb{R}$
- 2 $\|x + y\| \leq \|x\| + \|y\|$ (triangle inequality)
- 3 If $\|x\| = 0$ then $x = 0$

The distance between two vectors is then defined as

$$d(x, y) = \|x - y\|.$$

The most well-known and widely used norm is **euclidean norm**:

$$\|x\|_2 = \sqrt{\sum_{i=1}^n |x_i|^2},$$

which corresponds to the distance in our real life. If the vectors have complex elements, we use their modulus.

Euclidean norm, or 2-norm, is a subclass of an important class of p -norms:

$$\|x\|_p = \left(\sum_{i=1}^n |x_i|^p \right)^{1/p}.$$

There are two very important special cases:

- Infinity norm, or Chebyshev norm is defined as the element of the maximal absolute value:

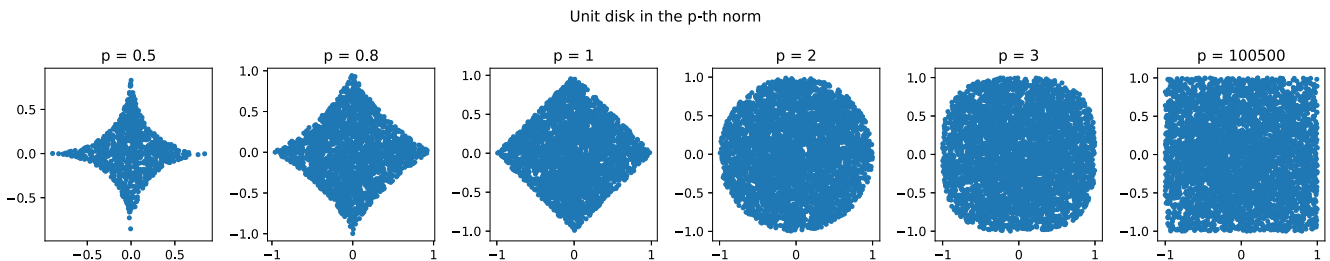
$$\|x\|_{\infty} = \max_i |x_i|$$

- L_1 norm (or **Manhattan distance**) which is defined as the sum of modules of the

elements of x :

$$\|x\|_1 = \sum_i |x_i|$$

L_1 norm plays very important role: it all relates to the **compressed sensing** methods that emerged in the mid-00s as one of the most popular research topics. The code for picture below is available here: [Open In Colab](#)



In some sense there is no big difference between matrices and vectors (you can vectorize the matrix), and here comes the simplest matrix norm **Frobenius** norm:

$$\|A\|_F = \left(\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2 \right)^{1/2}$$

Spectral norm, $\|A\|_2$ is one of the most used matrix norms (along with the Frobenius norm).

$$\|A\|_2 = \sup_{x \neq 0} \frac{\|Ax\|_2}{\|x\|_2}$$

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It can not be computed directly from the entries using a simple formula, like the Frobenius norm, however, there are efficient algorithms to compute it. It is directly related to the **singular value decomposition** (SVD) of the matrix. It holds

$$\|A\|_2 = \sigma_1(A) = \sqrt{\lambda_{\max}(A^T A)}$$

where $\sigma_1(A)$ is the largest singular value of the matrix A .

QUESTION

Is it true, that all matrix norms satisfy submultiplicativity property: $\|AB\| \leq \|A\| \|B\|$? Hint: consider Chebyshev matrix norm $\|A\|_C = \max_{i,j} |a_{ij}|$.

The standard **scalar (inner) product** between vectors x and y from \mathbb{R}^n is given by

$$\langle X, X \rangle = \|X\|^2$$

$$\langle x, y \rangle = x^T y = \sum_{i=1}^n x_i y_i = y^T x = \langle y, x \rangle$$

$1 \times n$ $n \times 1$

Here x_i and y_i are the scalar i -th components of corresponding vectors.

QUESTION

Is there any connection between the norm $\| \cdot \|$ and scalar product $\langle \cdot, \cdot \rangle$?

EXAMPLE

$$= x^T A y$$

Prove, that you can switch the position of a matrix inside scalar product with transposition: $\langle x, Ay \rangle = \langle A^T x, y \rangle$ and $\langle x, yB \rangle = \langle xB^T, y \rangle$

The standard **scalar (inner) product** between matrices X and Y from $\mathbb{R}^{m \times n}$ is given by

$$\langle X, Y \rangle = \text{tr}(X^T Y) = \sum_{i=1}^m \sum_{j=1}^n X_{ij} Y_{ij} = \text{tr}(Y^T X) = \langle Y, X \rangle$$

$n \times m$ $m \times n$

QUESTION

$$\|X\|_F^2 = \langle X, X \rangle$$

Is there any connection between the Frobenious norm $\| \cdot \|_F$ and scalar product between matrices $\langle \cdot, \cdot \rangle$?

EXAMPLE

Simplify the following expression:

$$\sum_{i=1}^n \langle S^{-1} a_i, a_i \rangle, \text{ where } S = \sum_{i=1}^n a_i a_i^T, a_i \in \mathbb{R}^n, \det(S) \neq 0$$

▼ Solution 1) $\sum_{i=1}^n \langle S^{-1} a_i, a_i \rangle = \sum_{i=1}^n m_{ii} = \text{tr}(M)$

2) SKELETON $S = A \cdot A^T$, где $A = \begin{pmatrix} | & & | \\ a_1 & \dots & a_n \\ | & & | \end{pmatrix}_{n \times n}$, $A^T = \begin{pmatrix} -a_1^T \\ \vdots \\ -a_n^T \end{pmatrix}$; $S^{-1} = (A A^T)^{-1} = A^{-T} \cdot A^{-1} = S^{-T}$

3) $m_{ii} = a_i^T S^{-1} a_i$ Если $M = \underbrace{A^T}_{i\text{-as } a_i^T} \cdot \underbrace{S^{-1}}_{i\text{-bi } S^{-1}} \cdot A$ $S^{-1} = \begin{pmatrix} | & & | \\ a_1 & \dots & a_n \\ | & & | \end{pmatrix}$

4) $\sum = \text{tr}(A^T S^{-1} A) = \text{tr}(A A^T \cdot S^{-1}) = \text{tr}(S S^{-1}) = \text{tr} I = n$.